

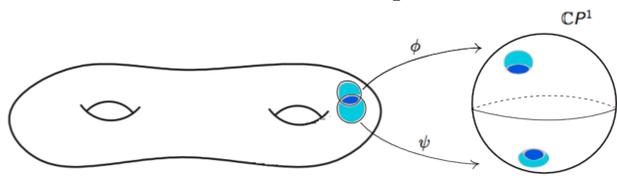
# $\mathbb{C}P^1$ -structures and dynamics in moduli space

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## What is a $\mathbb{C}P^1$ -structure?

A *complex projective structure* on a surface  $S$  is a choice of charts to  $\mathbb{C}P^1$  such that the transition maps lie in  $PSL(2, \mathbb{C})$ . It has a **developing map**  $f: \tilde{S} \rightarrow \mathbb{C}P^1$  and a **holonomy representation**  $\rho: \pi_1(S) \rightarrow PSL(2, \mathbb{C})$  that records the mismatch of charts around loops.



$\phi \circ \psi^{-1}$  is a Möbius map

*Example:* A **hyperbolic surface**, with charts to the hyperbolic plane  $\mathbb{H}^2$  thought of as the upper hemisphere of  $\mathbb{C}P^1$ , and transition maps in  $Isom^+(\mathbb{H}^2) = PSL_2(\mathbb{R}) \hookrightarrow PSL_2(\mathbb{C})$ . The holonomy is a **Fuchsian representation**.

## The bundle picture

Assume  $S$  is closed, oriented and of genus  $g \geq 2$ .

Let  $\mathcal{P}_g = \{\text{space of projective structures on } S\}$ .

Since the transition maps above are conformal, they also define a complex structure on  $S$ . So we have:

$$\begin{array}{c} \mathcal{P}_g \xrightarrow{h} \chi(S) \\ \downarrow \mathcal{T}_g \\ \mathcal{M}_g \end{array}$$

Here  $\mathcal{T}_g$  is the **Teichmüller space** of all “marked” Riemann surfaces, and  $\mathcal{M}_g$  is **Riemann’s moduli space**, the quotient by the action of the *mapping class group*.

$\chi(S)$  is the **character variety** of  $PSL(2, \mathbb{C})$ -representations of  $\pi_1(S)$  upto conjugation, and  $h$  maps a  $\mathbb{C}P^1$ -structure to its holonomy.

## A motivating question

**Given a representation  $\rho \in \chi(S)$ , what is the structure of the level set  $h^{-1}(\rho)$ ?**

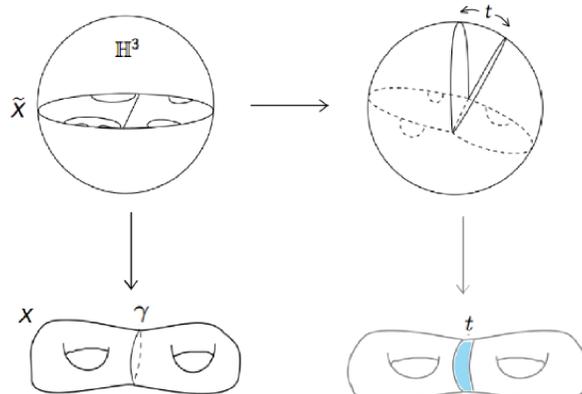
In 1983 Faltings conjectured that for  $\rho$  Fuchsian this set is infinite - this was shown to be true in [2]. More recently, work of Shinpei Baba shows that a generic level set is infinite.

## References

- [1] D. Dumas, *Complex projective structures*. In “Handbook of Teichmüller theory” Vol. II, EMS Zürich, 2004.
- [2] W. Goldman, *Projective structures with Fuchsian holonomy*. J. Differential Geom. Vol 25 No. 3, 1987.
- [3] S. Gupta, *Asymptoticity of grafting and Teichmüller rays I*. <http://arxiv.org/abs/1109.5365>
- [4] —, *Meromorphic quadratic differentials with half-plane structures*. <http://arxiv.org/abs/1301.0332>
- [5] —, *Conformal limits of grafting and Teichmüller rays*. <http://arxiv.org/abs/1303.7387>
- [6] H. Masur, *Interval exchange transformations and measured foliations*. Ann. of Math. (2), Vol. 115 No.1, 1982.

## Bending and grafting

Given a hyperbolic surface  $X$  and a simple closed geodesic  $\gamma$ , one can deform the  $\mathbb{C}P^1$ -structure by *bending* the developing map.



This amounts to grafting in a euclidean cylinder at  $\gamma$ . More generally, one can graft along a **lamination**  $\lambda$ , which is a *limit* of curves.

The “bending angle” gives a one-parameter family of deformations

$$\{gr_{t\lambda}X\}_{t \geq 0}$$

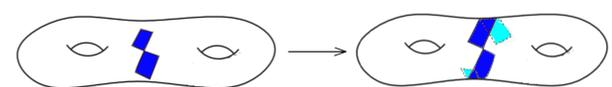
whose projection to  $\mathcal{T}_g$  is a **grafting ray**.

## Teichmüller geodesic rays

For two Riemann surfaces  $X$  and  $Y$  one can construct **quasiconformal maps** between them that allow a bounded distortion of angle.

For each such  $f$ , this distortion is some quantity  $K$  and the **Teichmüller distance** is given by the *least* distortion map:

$$d_{\mathcal{T}}(X, Y) = \frac{1}{2} \inf_f \ln K$$



Such a map picks a decomposition of the surface into rectangles, and stretches horizontally along each (*the figure above gives a partial picture*).

Given  $X$  and a horizontal foliation  $\lambda$ , the *stretch factor* parametrizes a geodesic path

$$\{\text{Teich}_{t\lambda}X\}_{t \geq 0}$$

in  $\mathcal{T}_g$  which is a **Teichmüller ray**.

## Our results

**Theorem 1.** Let  $X \in \mathcal{T}_g$  and  $\lambda$  any lamination. Then there exists a  $Y \in \mathcal{T}_g$  such that the grafting ray determined by  $(X, \lambda)$  is **strongly asymptotic** to the Teichmüller ray determined by  $(Y, \lambda)$ , that is,

$$d_{\mathcal{T}}(gr_{e^{t\lambda}}X, \text{Teich}_{t\lambda}Y) \rightarrow 0$$

as  $t \rightarrow \infty$ .

By the *ergodicity* of the Teichmüller geodesic flow (see [6]), we have:

**Corollary.** Almost every grafting ray projects to a dense set in  $\mathcal{M}_g$ .

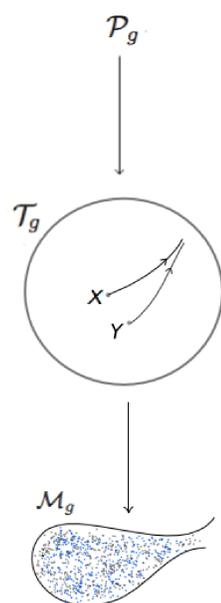
**Theorem 2.** Let  $X \in \mathcal{T}_g$ . Then the set

$$\mathcal{S} = \{gr_{2\pi\gamma}X \mid \gamma \text{ is a multicurve}\}$$

projects to a **dense set** in moduli space  $\mathcal{M}_g$ .

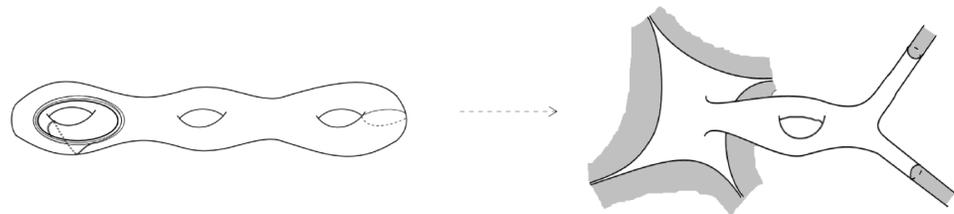
Since these “ $2\pi$ -graftings” preserve Fuchsian holonomy we get:

**Corollary.** For  $\rho$  a Fuchsian representation,  $h^{-1}(\rho)$  projects to a dense set in  $\mathcal{M}_g$ .



## Idea of the proof of the asymptoticity result

- Take a **conformal limit** of the grafting ray as  $t \rightarrow \infty$ :



The “infinitely-grafted surface” is obtained by gluing in euclidean half-planes and half-infinite cylinders to the complement of the lamination.

- “Uniformize” this to an infinite-area *singular flat surface* by prescribing a **meromorphic quadratic differential with higher order poles**. This shall be the “limit” of the asymptotic Teichmüller ray.
- Use **quasiconformal cut-and-paste** to adjust this uniformizing map to an *almost-conformal* map between surfaces along the rays.