

## Solutions to Exercises 14

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1. Let  $(x, y), (u, v) \in \mathbb{R}^2$  and  $\lambda \in \mathbb{R}$ .
  - (a)  $T(\lambda(x, y) + (u, v)) = T(\lambda x + u, \lambda y + v) = (\lambda y + v, \lambda x + u) = \lambda(y, x) + (v, u) = \lambda T(x, y) + T(u, v)$ . Hence  $T$  is linear.
  - (b)  $T$  is not linear. For example  $T(2, 2) = (4, 4) \neq T(1, 1) + T(1, 1) = (2, 2)$ .
  - (c) Suppose  $T$  maps each point on to its reflection with respect to a fixed line  $L$  through the origin. If  $L$  is given by  $L := y = mx$  then  $T$  is given by the following,

$$T(x, y) = \begin{pmatrix} \frac{1-m^2}{1+m^2} & \frac{2m}{1+m^2} \\ \frac{2m}{1+m^2} & \frac{m^2-1}{1+m^2} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

Now it is straight forward to show that,  $T(\lambda(x, y) + (u, v)) = \lambda T(x, y) + T(u, v)$  and hence  $T$  is linear.

2. Let  $(x_1, x_2, x_3), (y_1, y_2, y_3) \in \mathbb{R}^3$  and  $\lambda \in \mathbb{R}$ 
  - (a)  $T$  is linear as  $T(\lambda(x_1, x_2, x_3) + (y_1, y_2, y_3)) = T(\lambda x_1 + y_1, \lambda x_2 + y_2, \lambda x_3 + y_3) = (\lambda x_3 + y_3, \lambda x_2 + y_2, \lambda x_1 + y_1) = \lambda(x_3, x_2, x_1) + (y_3, y_2, y_1) = \lambda T(x_1, x_2, x_3) + T(y_1, y_2, y_3)$ .  
 $N(T) = \{0\}$  and  $R(T) = \mathbb{R}^3$  and so the nullity of  $T$  is 0 and rank of  $T$  is 3.
  - (b)  $T$  is not linear: eg.  $T(0, 2, 0) = (0, 4, 0), T(0, 1, 0) = (0, 1, 0) \Rightarrow T(0, 2, 0) \neq T(0, 1, 0) + T(0, 1, 0)$ .
  - (c)

$$T(x, y, z) = (x + z, 0, x + y) = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

It is easy to check that  $T(\lambda(x_1, x_2, x_3) + (y_1, y_2, y_3)) = \lambda T(x_1, x_2, x_3) + T(y_1, y_2, y_3)$  and so  $T$  is linear.

$$N(T) = \{(x, y, z) \in \mathbb{R}^3 | x + z = 0, x + y = 0\} \\ = \{(x, -x, -x) \in \mathbb{R}^3\} = \{x(1, -1, -1) | x \in \mathbb{R}\} = LS\{(1, -1, -1)\}.$$

$$R(T) = \{(x + z, 0, x + y) \in \mathbb{R}^3\} = \{(a, 0, b) | a, b \in \mathbb{R}\}.$$

$$Nullity(T) = 1, Rank(T) = 2.$$

3.  $S, T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  linear transformations given by,  $T(x, y, z) = (x, x + y, x + y + z), S(x, y, z) = (z, y, x)$ . Then  $S^{-1} = S$  and  $T^{-1}(x, y, z) = (x, y - x, z - y)$ .
  - (a)  $ST(x, y, z) = S(x, x + y, x + y + z) = (x + y + z, x + y, x)$   
 $TS(x, y, z) = T(z, y, x) = (z, z + y, z + y + x)$

$$(ST - TS)(x, y, z) = ST(x, y, z) - TS(x, y, z) = (x + y, x - z, -y - z).$$

(b)  
 $S(x, y, z) = 0 \Rightarrow (z, y, x) = 0 \Rightarrow x = y = z = 0$ , hence  $S$  is one-to-one.  
 $S^{-1} = S$ ,  $T^{-1}(x, y, z) = (x, y - x, z - y)$ ,  $(ST)^{-1} = T^{-1}S^{-1}(u, v, w) =$   
 $T^{-1}(w, v, u) = (w, v - w, u - v)$ ,  $(TS^{-1}(u, v, w) = S^{-1}T^{-1}(u, v, w) =$   
 $S^{-1}(u, v - u, w - v) = (w - v, v - u, u)$

(c)  
For  $n = 1$ ,  $(T - I)(x, y, z) = (x, x + y, x + y + z) - (x, y, z) = (0, x, x + y)$   
For  $n = 2$ ,  $(T - I)^2(x, y, z) = (T - I)(0, x, x + y) = (0, 0, x)$   
For  $n = 3$ ,  $(T - I)^3(x, y, z) = (0, 0, 0)$  and hence  $(T - I)^n = 0$ , for all  $n > 2$ .

4. Suppose  $S, T : \mathbb{R}^n \rightarrow \mathbb{R}^n$  are linear transformations such that  $ST - TS = I$ .  
Now  $ST^n - T^nS = (TS + I)T^{n-1} - T^nS = TST^{n-1} + T^{n-1} - T^nS$   
 $= T(TS + I)T^{n-2} + T^{n-1} - T^nS = T^2ST^{n-2} + 2T^{n-1} - T^nS$   
 $= \dots = T^nS + nT^{n-1} - T^nS = nT^{n-1}$

5. The matrix  $m(T)$  for the projection  $T$  is given by,

$$m(T) = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix}$$

Note that

$$T(x_1, x_2, x_3, x_4, x_5) = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix}$$

6.  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  linear, so  $T(e_1 + e_2) = T(e_1) + T(e_2)$  and  $T(3e_1 + 2e_2) = 3T(e_1) + 2T(e_2)$ . Hence we have following two equations,  
 $T(e_1) + T(e_2) = 3e_1 + 9e_2$  and  
 $3T(e_1) + 2T(e_2) = 7e_1 + 23e_2$ .  
Solving above two equations we have  $T(e_1) = e_1 + 5e_2$ ,  $T(e_2) = 2e_1 + 4e_2$ .  
(a)  $T(e_2 - e_1) = T(e_2) - T(e_1) = e_1 - e_2$   
(b) The matrix of  $T$  with respect to standard ordered basis of  $\mathbb{R}^2$  is given by

$$m(T) = \begin{pmatrix} 1 & 2 \\ 5 & 4 \end{pmatrix}$$

7. Let,

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

and  $A^2 = 0$ , then  $\text{trace}(A) = a + d = 0 \Rightarrow d = -a$ , and  $A^2$  is given by,

$$\begin{bmatrix} a^2 + bc & 0 \\ 0 & a^2 + bc \end{bmatrix}$$

Hence  $a^2 + bc$  must be 0.

8.

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} = \begin{pmatrix} ad - bc & 0 \\ 0 & ad - bc \end{pmatrix} = (ad - bc) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Now,  $A$  is nonsingular  $\Leftrightarrow \det(A) \neq 0 \Leftrightarrow ad - bc \neq 0$ . From the above equation it follows that,

$$A^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

9.  $A$  and  $B$  are nonsingular does not imply that  $A+B$  is not nonsingular. For example consider any nonsingular matrix  $A$  and  $B = -A$ , then  $B$  is also nonsingular. But  $A + B = 0$  in singular matrix.

10. Given that  $A^2 = A$ . To show that,  $(A + I)^k = I + (2^k - 1)A$ . We will proceed by mathematical induction.

*step - 1.*  $k = 0$ .

$(A + I)^0 = I$  and  $I + (2^0 - 1)A = I$ . So the statement is true for  $k = 0$ .

*step - 2.* Assume that the statement is true for  $k$ .

*step - 3*  $(A + I)^{k+1} = (A + I)^k(A + I) = \{I + (2^k - 1)A\}(A + I) = A + I + (2^k A - A)(A + I) = A + I + 2^k A^2 + 2^k A - A^2 - A = I + (2^{k+1} - 1)A$ .

(Using  $A^2 = A$ )